STELLA MARIS COLLEGE (AUTONOMOUS) CHENNAI 600 086 (For candidates admitted during the academic year 2009 – 10 & thereafter)

SUBJECT CODE : MT/PC/CM34

M. Sc. DEGREE EXAMINATION, NOVEMBER 2011 BRANCH I - MATHEMATICS THIRD SEMESTER

COURSE	:	CORE
PAPER	:	CONTINUUM MECHANICS
TIME	:	3 HOURS

MAX. MARKS : 100

$SECTION - A \qquad (5 X 8 = 40)$ ANSWER ANY FIVE QUESTIONS

1. If the stress sensor $\sigma_{ij} = \begin{pmatrix} \sigma & a\sigma & b\sigma \\ a\sigma & \sigma & c\sigma \\ b\sigma & c\sigma & \sigma \end{pmatrix}$, determine the constants a,b,c so that the

stress vector on the octahedral plane $\left(\hat{n} = \frac{1}{\sqrt{3}}\hat{e_1} + \frac{1}{\sqrt{3}}\hat{e_2} + \frac{1}{\sqrt{3}}\hat{e_3}\right)$ vanishes.

2. Determine the principal deviator stress values for the stress tensor

$$\sigma_{ij} = \begin{pmatrix} 10 - 6 & 0 \\ -6 & 10 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

3. The displacement field of continuum body is given by $x_1 = X_1$, $x_2 = X_2 + AX_3$,

 $x_3 = x_3 + AX_2$, where A is constant. Determine the displacement vector components in both the material and spatial form.

4. A velocity field is given by $v_1 = \frac{x_1}{(1+t)}, v_2 = \frac{2x_2}{(1+t)}, v_3 = \frac{3x_3}{(1+t)}$. Obtain the

displacement relations $x_i = x_i(X, t)$ and determine the acceleration components in Lagrangian form for the motion.

- 5. For the steady velocity field $v = 3x_1^2x_2\hat{e}_1 + 2x_2^2x_3\hat{e}_2 + 3x_1x_2x_3^2x_2\hat{e}_3$, determine the rate of extension at P(1,1,1) in the direction of $v = \frac{1}{5}(3\hat{e}_1 4\hat{e}_3)$.
- 6. (a) Show that the velocity field $v_i = Ax_i / r^3$ where $x_i x_i = r^2$ and A is an arbitrary constant, satisfies the continuity equation for an incompressible flow.
 - (b) For the velocity field $v_i = \frac{x_i}{(1+t)}$ show that $\rho x_1 x_2 x_3 = \rho_0 X_1 X_2 X_3$.
- 7. Express the engineering constants ν and E in terms of the Lame' constants λ and μ .

SECTION – B $(3 \times 20 = 60)$ ANSWER ANY THREE QUESTIONS

8. (a) Establish the relation between the stress tensor and the stress vector.

(b) Evaluate the stress invariants for the stress tensor
$$\sigma_{ij} = \begin{pmatrix} 6 & -3 & 0 \\ -3 & 6 & 0 \\ 0 & 0 & 8 \end{pmatrix}$$
.

9. (a) A displacement field is given by $= X_1 X_3^2 \hat{e}_1 + X_1^2 X_2 \hat{e}_2 + X_2^2 X_3 \hat{e}_3$. Determine

independently the material deformation gradient F and the material displacement gradient J and verify J=F-I.

- (b) A continuum body undergoes the deformation $x_1 = X_1, x_2 = X_2 + AX_3, x_3 = X_3 + AX_2$ where A is constant. Compute the deformation tensor G and use this to determine the Lagrangian finite strain tensor L_G .
- 10. (a) A displacement field is specified by $\boldsymbol{u} = X_1^2 X_2 \hat{e}_1 + (X_2 X_3^2) \hat{e}_2 + X_2^2 X_3 \hat{e}_3$.

Determine the relative displacement vector du in the direction of the $-X_2$ axis at P(1, 2, -1). Determine the relative displacements

 $u_{q_i} - u_p$ for $Q_1(1,1,-1)$, $Q_2(1,3/2,-1)$, $Q_3(1,7/4,-1)$ and $Q_4(1,15/8,-1)$ and compare their direction with the direction of du.

- (b) Explain the terms: Material derivative, Local rate of change, convective rate of change and Material derivative operator.
- 11. (a) A steady velocity field is given by $\vec{v} = (x_1^3 x_1 x_2^2)\hat{e}_1 + (x_1^2 x_2 x_2)\hat{e}_2$. Determine the unit relative velocity with respect to P(1,1,3) of the particles at

$$Q_1(1,0,3), Q_2(1,\frac{3}{4},3), Q_3(1,\frac{7}{8},3).$$

- (b) Using linear momentum principle, obtain the equations of motion of a moving continuum.
- 12. Obtain the generalised Hooke's law for an isotropic body in terms of the elastic

constants λ and μ . Show that the strain energy density function u^* for an isotropic Hookean solid may be expressed in terms of the strain tensor by $u^* = \frac{\lambda}{2} \varepsilon_{ii} \varepsilon_{jj} + \mu \varepsilon_{ij} \varepsilon_{ij}$.